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1.1 Mathematical Modeling of Robots 3 1.1.1 Symbolic Representation of Robots 3 1.1.2 The Configuration Space 4 1.1.3 The State Space 5 1.1.4 The Workspace 5 1.2 Robots as Mechanical Devices 5 ... degree of autonomy, usually under computer control, has at some point been called a robot. In this text the term robot will mean a computer controlled

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